

Ruter Shared AVs Dialogue Conference

Mobileye L4 MaaS

Mobility-As-A-Service Group

June 2022



Mobileye Mobility-As-A-Service: Building technology and partnerships to bring Autonomous Mobility-as-a-Service Fleets to the streets.



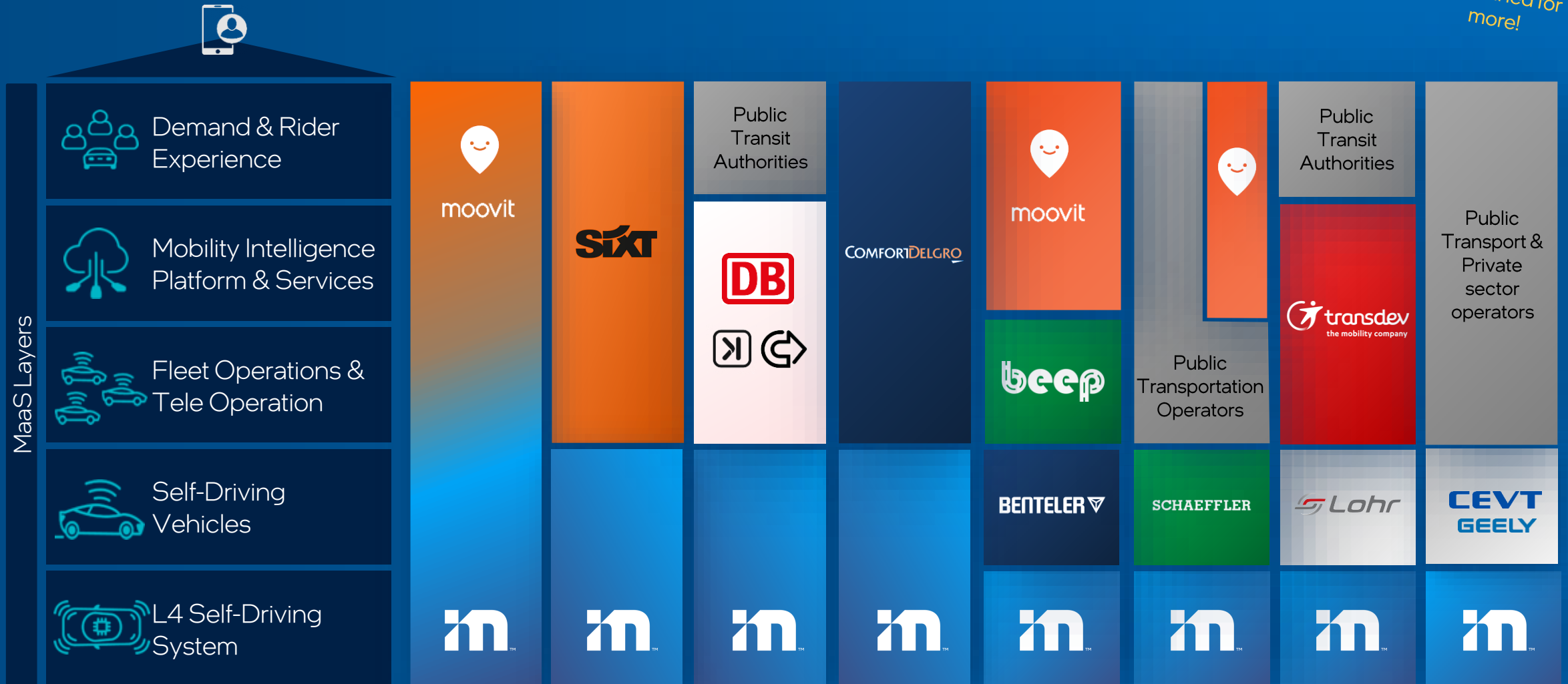
Status Quo 2022

Mobileye Robotaxi Driverless Roll-out Expected to Start End of 2022 Pending Regulatory Approvals



Autonomous MaaS Collaborations Highlights Along Value Chain

Stay tuned for more!



Safety & Scalability: Largest Global Footprint in the AV Industry



Mobileye Drive™ supports all autonomous usecases

Vehicle types	Small Pods (0-3 passengers)	Pods/Robotaxis (~4-6 passengers, Medium-sized)	AV Shuttles (8-18 passengers)	AV Busses (19+ passengers)	AV Transporter (Special Purpose Pods; non- passenger focused interior)	AV Trucks
Usecases						
Ridehailing / Private Robotaxi	✓	✓				
Ridepooling / Demand-Responsive Transport (on-demand)		✓	✓			
Autonomous public transport (as part of (sub)urban transit, Metro/Bus-Mode)		✓	✓	✓		
Additional public transport (suburban/rural; to transit hubs, inter-village, etc.)		✓	✓			
Last mile delivery, Autonomous parcel lockers	✓				✓	
Medium-Mile & Long-haul logistics					✓	✓
Closed confined area use cases (employee transport, trade fairs, airport/harbors, etc.)		✓	✓	✓	✓	



Mobileye Drive™ vehicle portfolio (value proposition 2024+)

Category	Item 1	Item 2	Item 3	Item 4	Item 5
Category 1	✓	✓	✓	✓	✓
Category 2	✓	✓	✓	✓	✓
Category 3	✓	✓	✓	✓	✓
Category 4	✓	✓	✓	✓	✓
Category 5	✓	✓	✓	✓	✓
Category 6	✓	✓	✓	✓	✓
Category 7	✓	✓	✓	✓	✓
Category 8	✓	✓	✓	✓	✓
Category 9	✓	✓	✓	✓	✓
Category 10	✓	✓	✓	✓	✓

Vehicle types:

Pods/Robotaxis

(~4-6 passengers,
medium-sized)

AV Shuttles

(8-18 passengers)

AV Busses

(19+ passengers)

Use cases:

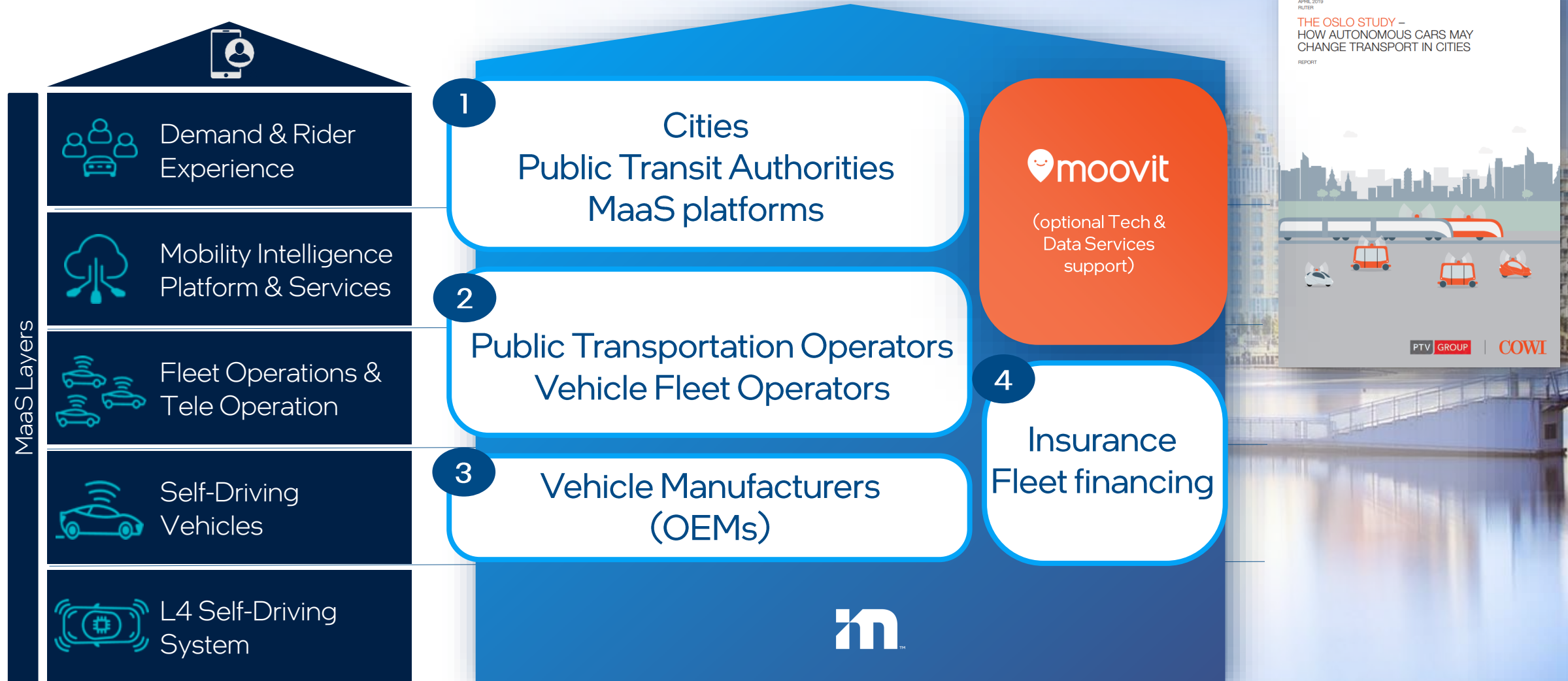
Ridepooling / Demand-Responsive Transport (on-demand)

Autonomous public transport
(as part of (sub)urban transit, Metro/Bus-Mode)

Additional public transport
(suburban/rural; to transit hubs, inter-village, etc.)



Call for action



Thank you for your attention!





mobileye®

An Intel Company

The Right Thing To Do: Driverless Inclusive Mobility for All!



Safe



Accessible



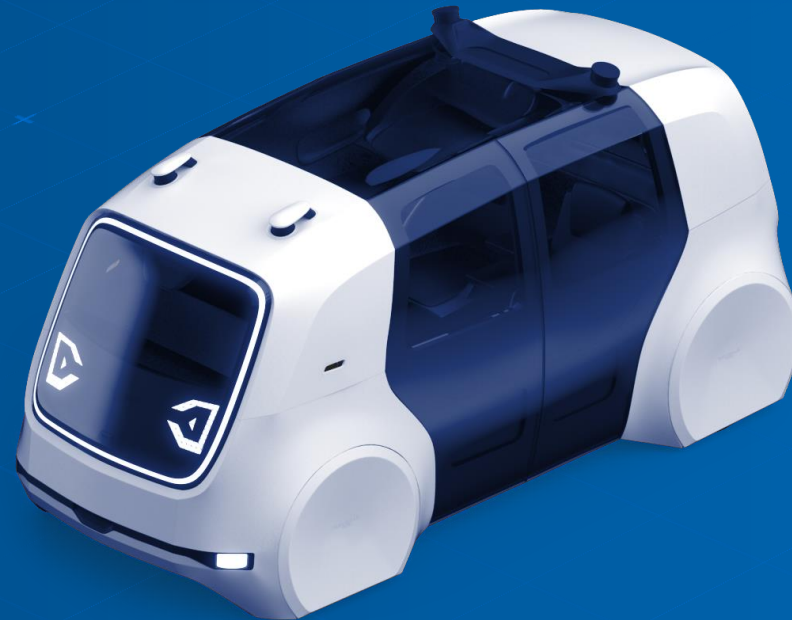
Clean



Affordable



Convenient



Mobileye's USPs – The Trinity Approach

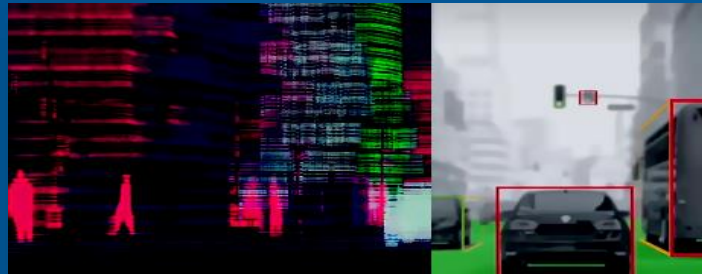
REM™-BASED AV MAPS

- REM™-enabled scalability
AV Map Key to high MTBF
- Crowdsource data collection followed by auto AV map creation in the cloud



TRUE REDUNDANCY™

- Two independent subsystems to increase robustness & MTBF



RESPONSIBILITY-SENSITIVE SAFETY (RSS)

- Generalized driving policy
- formal safety model decision-making governance
- Standardizing human judgement (IEEE P2846)

On a Formal Model of Safe and Scalable Self-driving Cars

Shai Shalev-Shwartz, Shaked Shammah, Amnon Shashua
Mobileye, 2017

$$\begin{aligned} \mathbb{P}[e^m] &= \mathbb{P}[e_1^m \wedge e_2^m \wedge e_3^m] + \sum_{j=1}^3 \mathbb{P}[e_j^m \wedge e_1^m \wedge e_2^m \wedge e_3^m] + \sum_{j=1}^3 \mathbb{P}[e_j^m \wedge e_1^m \wedge e_2^m \wedge e_3^m] \\ &= \sum_{j=1}^3 \mathbb{P}[\bigwedge_{i \neq j} e_i^m] \\ &< c \sum_{j=1}^3 \prod \mathbb{P}[e_i^m] \end{aligned}$$

Autonomous MaaS with Moovit App & MaaS Platform

