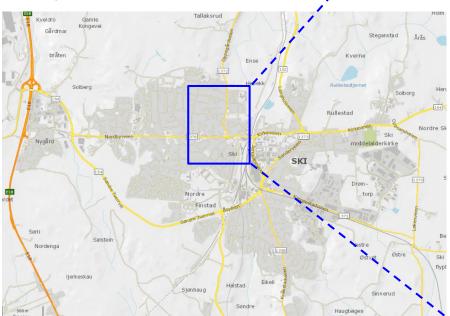


Initial Ski test area

Initial test area is focused on the neighbourhood of Hebekk.

Route already active with Sensible 4 / Toyota vehicles



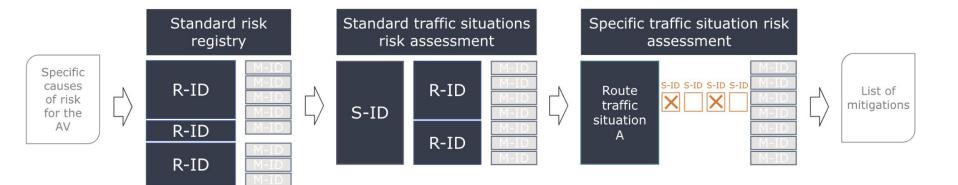


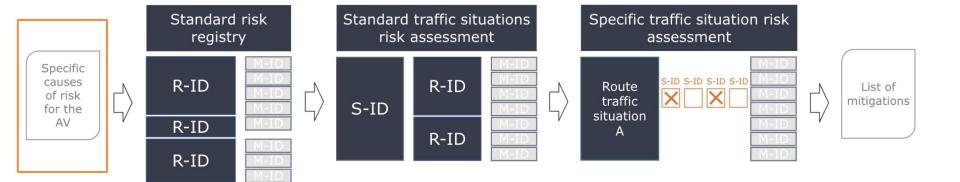
Test area 2.0?

As soon as technology makes it possible, the area should be expanded to cover all of Ski.

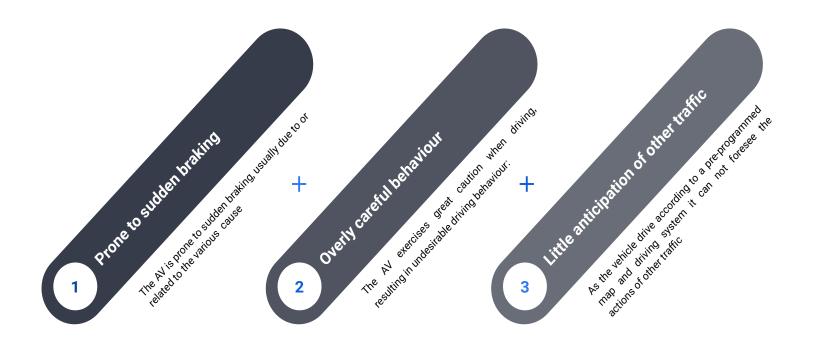
How can we scale up risk assessment?

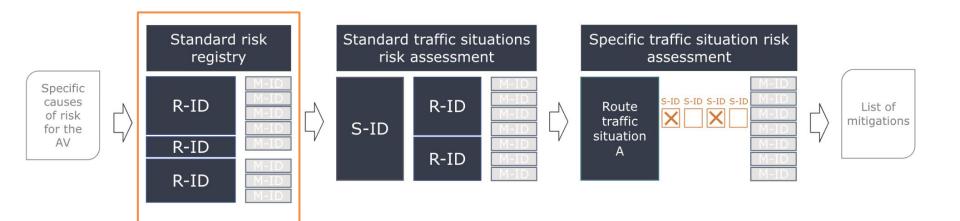






Specific causes of risk for the AV





Standard risks are derived from the specific causes of risk

| Risk (R-ID) | | | Causes | | | Unwanted scenar | rios | | | Standard traffic scena (S-ID) | | | | | ari | 0 | | |
|-------------------------------|---|------------|-----------------------------------|---------|---|--------------------|-------|--|---|-------------------------------|---|---|---|---|-----|---|---|----|
| Title | Description | Risk score | Causes | Cause i | mitigations | Consequences | Conse | quence mitigations | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| Sudden breaking on road | Sudden detection of objects causes the | | Ghost detection | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. | due to sudden | | Adding signs in the area informing other road users of the AVs operating. | | | | | | | | | | |
| | bus to break. | 3B | Sudden loss of localisation | | Signs on the back of AV urging other road users not to overtake the AV | overtakings due to | | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops | | | | | | | | | | |
| | | | [] | [] | [] | [] | [] | [] | × | | | × | | | × | | × | |

Causes of risks are derived as well as potential mitigations

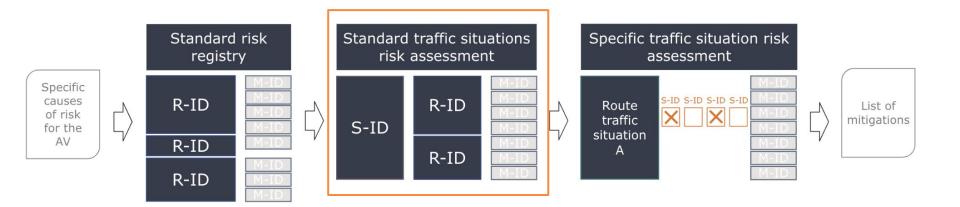
| Risk (R-ID) | | | Causes | | | Unwanted scenar | rios | | Standard traffic scena (S-ID) | | | | | ari | D | | | |
|-------------------------------|---|------------|-----------------------------------|--------|---|--------------------|-------|--|----------------------------------|---|---|---|---|-----|---|---|---|----|
| Title | Description | Risk score | Causes | Cause | mitigations | Consequences | Conse | quence mitigations | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| Sudden breaking on road | Sudden detection of objects causes the | | Ghost detection | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. | | | Adding signs in the area informing other road users of the AVs operating. | | | | | | | | | | |
| | bus to break. [] | 3B | Sudden loss of localisation | M-ID 2 | Signs on the back of AV urging other road users not to overtake the AV | overtakings due to | | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops | | | | | | | | | | |
| | | | [] | [] | [] | [] | [] | [] | × | | | x | | | × | | × | |

As well as risk related consequenses and associated mitigations

| Risk (R-ID) | | | Causes | | | Unwanted scenar | rios | | | Standard traffic scenar (S-ID) | | | | | ario |) | | |
|-------------------------------|---|------------|-----------------------------------|--------|---|--------------------|--------|--|---|-----------------------------------|---|---|---|---|------|---|---|----|
| Title | Description | Risk score | Causes | Cause | mitigations | Consequences | Conse | quence mitigations | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| Sudden breaking on road | Sudden detection of objects causes the | | Ghost detection | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. | due to sudden | | Adding signs in the area informing other road users of the AVs operating. | | | | | | | | | | |
| | bus to break. [] | 3B | Sudden loss of localisation | M-ID 2 | Signs on the back of AV urging other road users not to overtake the AV | overtakings due to | M-ID 3 | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops | | | | | | | | | | ļ |
| | | | [] | [] | [] | [] | [] | [] | x | | | x | | | × | | X | |

For each standard risk it is identified which standard traffic situations it might be relevant for.

| Risk (R-ID) | | | Causes | | | Unwanted scenar | rios | | Standard traffic scena (S-ID) | | | | | ena | ario |) | | |
|-------------------------------|---|------------|-----------------------------------|--------|---|--------------------|--------|--|----------------------------------|---|---|---|---|-----|------|---|---|----|
| Title | Description | Risk score | Causes | Cause | mitigations | Consequences | Conse | quence mitigations | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| Sudden breaking on road | Sudden detection of objects causes the | | Ghost detection | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. | due to sudden | | Adding signs in the area informing other road users of the AVs operating. | | | | | | | | | | |
| | bus to break. [] | 3B | Sudden loss of localisation | M-ID 2 | Signs on the back of AV urging other road users not to overtake the AV | overtakings due to | M-ID 3 | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops | | | | | | | | | | |
| | | | [] | [] | [] | [] | [] | [] | X | | | × | | | × | | X | |



Standard traffic situations risk assessment

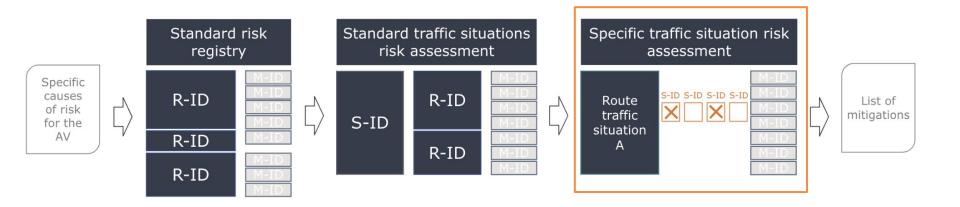
Transposing the risk registry to obtain risks per standard scenarios

| Standard scenario ID (S-ID) | Standard situation | Risk ID (R-ID) | Risk description | Risk Matrix score | Mitigation ID (M-ID) | Risk Mitigations |
|--------------------------------|-----------------------|-------------------|----------------------------|----------------------|-------------------------|---|
| S-ID 1 | Straight | R-ID 1 | Sudden | | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. |
| | through intersection | | breaking on road | | M-ID 2 | Signs on the back of AV urging other road users not to overtake the AV |
| | | | | | M-ID 3 | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops |
| | | | | 3B | M-ID 5 | Trim vegetation limiting blind spots |
| | | | | | M-ID 8 | Establish yield for crossing vehicles |
| | | | | | M-ID 9 | Establish unconditional yield in intersection |
| | | | | | M-ID 10 | Adding line markings prohibiting overtakings |
| | | R-ID 4 | Slow to start after POI or | | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. |
| | | | trajectory is | 2C | M-ID 2 | Signs on the back of AV urging other road users not to overtake the AV |
| | | | clear | | M-ID 3 | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops |

Standard traffic situations risk assessment

Transposing the risk registry to obtain risks per standard scenarios

| Standard scenario ID (S-ID) | Standard situation | Risk ID (R-ID) | Risk description | Risk Matrix score | Mitigation ID (M-ID) | Risk Mitigations |
|--------------------------------|-----------------------|-------------------|-------------------------------|----------------------|-------------------------|---|
| | Straight | R-ID 1 | Sudden | | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. |
| | through intersection | | breaking on road | | M-ID 2 | Signs on the back of AV urging other road users not to overtake the AV |
| | | | | | M-ID 3 | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops |
| | | | | 3B | M-ID 5 | Trim vegetation limiting blind spots |
| | | | | | M-ID 8 | Establish yield for crossing vehicles |
| | | | | | M-ID 9 | Establish unconditional yield in intersection |
| | | | | | M-ID 10 | Adding line markings prohibiting overtakings |
| | | R-ID 4 | Slow to start after POI or | | M-ID 1 | Adding signs in the area informing other road users of the AVs operating. |
| | | | trajectory is | 2C | M-ID 2 | Signs on the back of AV urging other road users not to overtake the AV |
| | | | clear | | M-ID 3 | Sign in the back end of the autonomous vehicle to warn vehicles of sudden stops |



Categorising all traffic situations on the route by predefined standards.

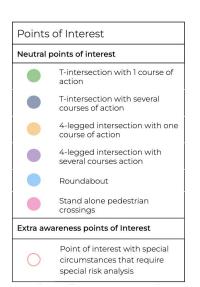
Automatically generating list of associated possible mitigations.

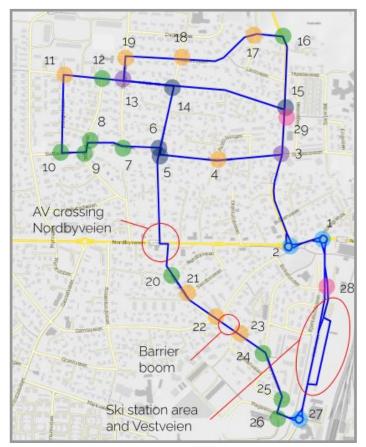
Risk score is re-assessed after activiation of potential mitigations.

| Specific traffic situation | | S-ID | S-ID 3 | | S-ID | Risk score before mitigations | Mitigation | | Active/ | Risk score after mitigations |
|-----------------------------|------------|------|-----------|---|------|-------------------------------------|------------|---|---------|------------------------------------|
| | | | | | | | | Adding signs in the area informing other road users of the AVs operating. | x | |
| Roundabout at | | | | | | 3B | | Signs on the back of AV urging other road users not to overtake the AV | х | 2B |
| Norbyveien and Vestveien | Roundabout | | | x | | | [] | [] | | |

Specific situations can be POIs or road sections







Som identified by data extracted from vegkart.no



Combining all specific traffic situations, their related risks and mitigations, a list of all unique mitigations is compiled.

